HP 8719C, 8720C, and 8722A/C network analyzers BASIC Programming Guide

for use with HP 9000 series 200/300 computers



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Programming Basics

Introduction

This manual is an introduction to remote operation of the HP 8719C, HP 8720C, or HP 8722A/C Network Analyzer using an HP 9000 series 200 or 300 computer. It is a tutorial introduction, using BASIC programming examples.

The reader should become familiar with the operation of the network analyzer before controlling it over HP-IB. This manual is not intended to teach BASIC programming or to discuss HP-IB theory; refer to the following documents which are better suited to these tasks.

■ For more information concerning the operation of the network analyzer, refer to the following:

HP 8719C/8720C User's Guide HP 8719C/8720C Reference Manual

For more information concerning BASIC, refer to the manual set for the BASIC revision being used:

BASIC Programming Techniques BASIC Language Reference

■ For more information concerning HP-IB, refer to the following:

HP-IB Programming Reference

BASIC Interfacing Techniques

Tutorial Description of the Hewlett-Packard Interface Bus

Condensed Description of the Hewlett-Packard Interface Bus

Start-up

Required Equipment

- 1. HP 8719C, HP 8720C, or HP 8722A/C Network Analyzer
- 2. HP 9000 Series 200 or 300 computer with enough memory to hold BASIC, needed binaries (refer to "Powering Up the System"), and at least 64 kilobytes of program space.
 - A disk drive is required to load BASIC, if no internal disk drive is available.
- 3. BASIC 3.0 or higher operating system.
- 4. HP 10833A/B/C/D HP-IB cables to interconnect the computer, the network analyzer, and any peripherals.

Optional Equipment

- 1. HP 85053B 3.5 mm calibration kit
- 2. HP 85132C Cable
- 3. Accessory kit
- 4. Device under test (DUT)
- 5. Cables to connect DUT
- 6. Printer

Powering Up the System

1. Set up the network analyzer as shown in Figure 1-1.

Connect the network analyzer to the computer with an HP-IB cable.

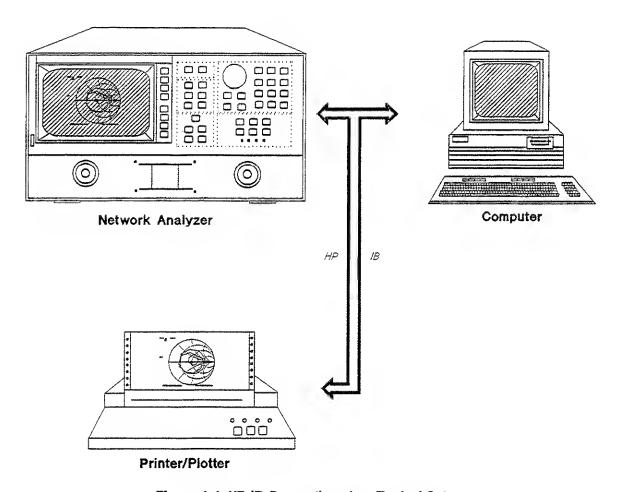


Figure 1-1. HP-IB Connections in a Typical Setup

2. Turn on the computer and load the BASIC operating system.

Load the following BASIC binary extensions:

HPIB, GRAPH, IO, KBD, and ERR.

Depending on the disk drive, a binary such as CS80 may be required.

3. Turn the network analyzer ON.

To verify the network analyzer's address, press (LOCAL) and select SET ADDRESSES ADDRESS: INSTRUMENT. If the address has been changed from the default value (16), return it to 16 while performing the examples in this document by pressing (1) (6) (x1) and the presetting the network analyzer.

Make sure the network analyzer is in the TALKER/LISTENER or USE PASS CONTROL mode, as indicated under the LOCAL key. These are the only modes in which the network analyzer will accept HP-IB commands.

4. On the computer, type the following:

OUTPUT 716; "PRES; " (Return) (or (EXECUTE))

This will preset the network analyzer. If preset does not occur, there is a problem. First check all HP-IB addresses and connections: most HP-IB problems are caused by an incorrect address and bad or loose HP-IB cables.

Note



Only the HP 9000 Model 226 and 236 computers have an EXECUTE key. The Model 216 has an EXEC key with the same function. All other computer use the Return key as both execute and enter. The notation Return is used in this document.

Measurement Programming

This section describes how to organize the commands into a measurement sequence. Figure 1-2 shows a typical measurement sequence.

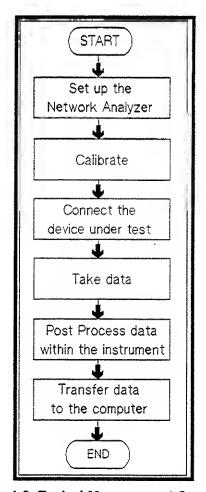


Figure 1-2. Typical Measurement Sequence

Setting up the network analyzer

Define the measurement by setting all of the basic measurement parameters. These include all the stimulus parameters: sweep type, span, sweep time, number of points, and RF power level. They also include the parameter to be measured, and both IF averaging and IF bandwidth. These parameters define the way data is gathered and processed within the instrument, and to change one requires that a new sweep be triggered.

There are other parameters that can be set within the network analyzer that do not affect data gathering directly, such as smoothing, trace scaling or trace math. These functions are classed as post processing functions: they can be changed with the network analyzer in the hold mode, and the data will correctly reflect the current state.

The save/recall registers provide a rapid way of setting up an entire instrument state.

Calibrating

Perform a measurement calibration once the network analyzer state has been defined. Measurement calibration is not required to make a measurement, but is highly recommend with microwave network analyzers in order to improve measurement accuracy.

There are several ways to calibrate the network analyzer as follows:

- □ Pause or stop the program and have the operator perform the calibration using the front panel keys.
- □ Guide the operator through the calibration under computer control, as discussed in "Frequency Response Calibration" in Chapter 2 and "1-Port Reflection Calibration" in Chapter 2.
- □ Transfer calibration data from a previous calibration back into the instrument, as discussed in "Reading Calibration Data" in Chapter 3.

■ Connecting device under test

Connect and adjust the device under test (DUT). The adjustment process can be assisted by setting specific network analyzer functions, such as limit testing, bandwidth searches, and trace statistics. All adjustments to the DUT should be performed at this stage.

■ Taking data

With the device connected and adjusted, command the network analyzer to take the measurement data for subsequent transfer.

The single sweep command SING is designed to ensure a valid sweep. When the sweep is complete, the network analyzer is put into the hold mode, storing the data inside the network analyzer. The number of groups command NUMGn is designed to work the same as single sweep, except that it triggers n sweeps. This is nseful when making a measurement with an averaging factor of n. Both single sweep and number of groups restart averaging.

Post-processing

With valid data to operate on, utilize the post-processing functions for analyzing the data. Referring to Figure 1-3, any function that affects the data after the error correction stage can be used. Some useful functions are trace statistics, marker searches, and electrical delay. If a 2-port calibration is active, then any of the fonr S-parameters can be viewed without taking a new sweep.

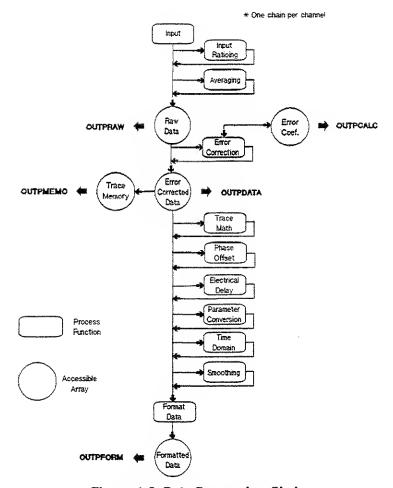


Figure 1-3. Data Processing Chain

■ Transferring data

Lastly, read the results out of the network analyzer. All the data output commands are designed to ensure that the data transmitted reflects the current state of the network analyzer:

- □ OUTPDATA, OUTPRAWn, OUTPFORM for transfer of entire data traces.
- □ OUTPLIML, OUTPLIMM, and OUTPLIMF for transfer of limit testing results.
- □ OUTPMARK for transfer of the currently active marker's results. This command will activate a marker if one is not already selected.
- DUTPMSTA for transfer of statistics that have been calculated for data between the active marker and the delta reference marker. If there is no delta reference, the entire trace data is used.
- DUTPMWID for transfer of the results of a bandwidth search.

Data transfer is discussed further in "Data Transfer from the Network Analyzer to a Computer" in Chapter 2.

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Basic Programming Examples

Setting Up a Measurement

In general, the procedure for setting up measurements on the network analyzer via HP-IB follows the same sequence as if the setup was performed manually. There is no required order, as long as the desired frequency range, number of points and power level are set prior to performing the calibration.

By interrogating the network analyzer to determine the actual values of the start, the stop, or the center frequencies, or the frequency span, the computer can keep track of the actual frequencies.

This example illustrates how a basic measurement can be set up on the network analyzer. The program will first select the desired parameter, the measurement format, and then the frequency range.

This example sets up a measurement of transmission log magnitude on channel 1. When prompted for the center frequency and the frequency span, enter any value in Hz from 1.0E+5 (for the S-parameter Test Set) to 5.0E+8. These will be entered into the network analyzer, and the frequencies will be displayed.

```
10
20
      ! Setting Up a Measurement
30
40
      Hp8720=716
      ABORT 7
50
60
      CLEAR Hp8720
70
80
      OUTPUT Hp8720; "PRES;"
      OUTPUT Hp8720; "CHAN1; S21; LOGM"
90
100
      INPUT "Enter center frequency (Hz)",F_cent
110
      INPUT "Enter frequency span (Hz)",F_span
120
      OUTPUT Hp8720; "CENT "; F_cent
130
      OUTPUT Hp8720; "SPAN "; F_span
140
150
      OUTPUT Hp8720; "CENT?"
160
      ENTER Hp8720; F_centr
170
      OUTPUT Hp8720; "SPAN?"
180
      ENTER Hp8720; F_spanr
190
      PRINT "Center frequency: ",F_centr; "Hz"
      PRINT "Frequency span: ",F_spanr; "Hz"
200
210
      END
```

Figure 2-1. Sample Program: Setting Up a Measurement

Line 40 Assigns network analyzer HP-IB address.

Lines 50 and 60 Prepares for HP-IB control.

Line 80 Presets the network analyzer.

Line 90 Makes channel 1 the active channel, and measures the transmission

parameter, S21, displaying its magnitude in dB.

Lines 100 and 110 Inputs the center frequency and the frequency span.

Lines 120 and 130 Sets the center frequency and the frequency span.

Lines 150 through 180 Queries the center frequency and the frequency span.

Lines 190 and 200 Shows the current center frequency and the frequency span.

Performing a Measurement Calibration

This section will demonstrate how to coordinate a measurement calibration over HP-IB. The HP-IB program follows the key strokes required to calibrate from the front panel: there is a command for every step.

The general keystrokes sequence is to select the calibration, measure the calibration standards, and then declare the calibration done. The actual sequence depends on the calibration kit and the calibration type.

Calibration Kits

The calibration kit tells the network analyzer what standards to expect at each step of the calibration. The set of standards associated with a given calibration is termed a class. Refer to the HP-IB Programming Reference for the relation between the calibration types and the standard classes.

For example, measuring the SHORT during a 1-port calibration is one calibration step. All of the SHORTs that can be used for this calibration step make up the class, which is called class S₁₁B. For the 7 mm calibration kits, class S₁₁B has only one standard in it. For the Type N calibration kit, class S₁₁B has two standards in it: male and female SHORTs.

When doing a 1-port calibration in 7 mm over HP-IB, sending CLASS11B will automatically measure the SHORT. In Type N, sending CLASS11B brings up the menu with the male and female SHORT options. To select a standard, use STANA or STANB. The STAN command is appended with the letters A through G, corresponding to the standards list under softkeys 1 through 7, softkey 1 being the topmost softkey.

Each full 2-port calibration is divided into three sub-sequences: transmission, reflection, and isolation. Each sub-sequence is treated like a calibration in its own right; each must be opened, have all the standards measured, and then be declared done. The opening and closing statements for the transmission sub-sequence are TRAN and TRAD. The opening and closing statements for the reflection sub-sequence are REFL and REFD. The opening and closing statements for isolation are ISOL and ISOD.

Frequency Response Calibration

The following program does a response calibration using a THRU calibration device. This program simplifies the calibration for the operator by giving explicit directions on the computer's display.

```
10
20
      ! Frequency Response Calibration
30
40
      Hp8720=716
50
      ABORT 7
60
      CLEAR Hp8720
70
80
      OUTPUT Hp8720; "PRES;"
90
      OUTPUT Hp8720; "CHAN1; S21; LOGM;"
100
      INPUT "Enter center frequency (Hz)",F_cent
110
      INPUT "Enter frequency span (Hz)", F_span
120
      OUTPUT Hp8720; "CENT"; F_cent
130
      OUTPUT Hp8720; "SPAN"; F_span
140
150
      OUTPUT Hp8720; "HOLD;"
160
      OUTPUT Hp8720; "CALK35MM;"
170
      OUTPUT Hp8720; "CALIRESP:"
180
      INPUT "Connect THRU, then press [Return].", Dum$
190
      OUTPUT Hp8720; "CLES;"
200
      OUTPUT Hp8720; "STANC;"
210
      REPEAT
220
        OUTPUT Hp8720; "ESB?;"
230
        ENTER Hp8720; Stat
240
     UNTIL BIT(Stat,0)
250
260
      OUTPUT Hp8720; "*OPC?; RESPDONE; "
270
      ENTER Hp8720; Dum
280
      OUTPUT Hp8720; "CONT;"
290
      DISP "Response cal completed."
300
      END
```

Figure 2-2. Sample Program: Frequency Response Calibration

Program explanation

Line 150	Sets the trigger to the hold mode.
Line 160	Selects the 3.5 mm calibration kit.
Line 170	Opens the calibration by calling the response calibration.
Line 180	Asks for a THRU, and waits for the operator to connect it.
Line 190	Clears all status registers.

Line 200	Selects and measures the THRU. There is more than one standard in this calibration, so we must identify the specific standard within this calibration. The THRU is the third softkey selection from the top in the menu, so use the STANC command to select THRU as the standard.
Lines 210 through 240	Waits for the standard to be measured. This is indicated by bit 0 of event status register B.
Lines 260 through 270	Affirms the completion of the calibration, and waits for calculation completion.

Line 280 Sets the trigger to the continuous mode.

1-Port Reflection Calibration

The following program does a 1-port calibration using the HP 85052D 3.5 mm calibration kit. This program simplifies the calibration for the operator by giving explicit directions on the computer display.

```
10
20
      ! 1-port Reflection Calibration
30
40
      Hp8720=716
50
      ABORT 7
60
      CLEAR Hp8720
70
80
      OUTPUT Hp8720; "PRES"
90
      OUTPUT Hp8720; "CHAN1;"
100
      INPUT "Enter center frequency (Hz)",F_cent
      INPUT "Enter frequency span (Hz)",F_span
110
120
      OUTPUT Hp8720; "CENT "; F_cent
130
      OUTPUT Hp8720; "SPAN "; F_span
140
150
      OUTPUT Hp8720; "HOLD;"
160
      OUTPUT Hp8720; "CALK35MM;"
170
      OUTPUT Hp8720; "CALIS111;"
180
      1
190
      INPUT "Connect OPEN at port 1, then press [Return].", Dum$
200
      OUTPUT Hp8720; "OPC; CLASS11A;"
210
      GOSUB Op_end
220
230
      INPUT "Connect SHORT at port 1, then press [Return].", Dum$
240
      OUTPUT Hp8720; "OPC; CLASS11B; "
250
      GOSUB Op_end
260
270
      INPUT "Connect LOAD at port 1, then press [Return].", Dum$
280
      OUTPUT Hp8720; "CLASS11C; OPC; STANA;"
290
      GOSUB Op_end
300
      OUTPUT Hp8720; "DONE;"
310
320
      OUTPUT Hp8720;"OPC?;"
330
      OUTPUT Hp8720; "SAV1;"
340
      ENTER Hp8720; Dum
350
      OUTPUT Hp8720; "CONT"
360
      DISP "1-port cal completed."
370
      STOP
380
      !
390 Op_end: !
400
     REPEAT
410
        OUTPUT Hp8720; "ESB?"
420
        ENTER Hp8720; Stat
430
     UNTIL BIT(Stat,0)
440
     RETURN
```

Figure 2-3. Sample Program: 1-port Reflection Calibration

Line 170	Opens the calibration by calling the S_{11} 1-port calibration.
Line 200 through 210	Selects the OPEN (S11A) class. Since there is only one standard in this class, only the class command needs to be sent. OPC (Operation Complete) along with the subroutine Op_end causes the program to wait under the measurement is completed.
Line 240 through 250	Selects the SHORT (S11B) class. Since there is only one standard in this class, only the class command needs to be sent. OPC (Operation Complete) along with the subroutine Op_end causes the program to wait under the measurement is completed.
Line 280	Selects the LOADS (S11C) class, followed by the BROADBAND load standard, and starts measuring the standard.
Line 320 through 330	Saves the calibration.
Line 350	Sets the trigger to the continuous mode.
Line 390 through 440	Waits until the operation complete bit of the event status register is set to 0.

Full 2-Port Measurement Calibration

The following example shows how to perform a full 2-port measurement calibration using the HP 85052D calibration kit. The main difference between this example and the preceding is that in this case, the calibration porcess allows removal of both the forward and reverse error terms, so that all four S-parameters of the device under test can be measured.

```
1
      ! Full 2-port measurement calibration.
3
      ! It guides the operator through a full 2-port calibration,
4
      ! using the HP 85052D 3.5 mm economy calibration kit (no sliding loads).
5
8
      Hp8720=716
10
      ABORT 7
20
      CLEAR Hp8720
30
      OUTPUT Hp8720; "CALK35MM; MENUOFF;"
40
      OUTPUT Hp8720; "CALIFUL2;"
50
      OUTPUT Hp8720; "REFL;"
60
      INPUT "CONNECT OPEN AT PORT 1", Dum$
70
      OUTPUT Hp8720; "OPC?; CLASS11A;"
08
      ENTER Hp8720; Reply
90
      INPUT"CONNECT SHORT AT PORT 1", Dum$
100
      OUTPUT Hp8720; "OPC?; CLASS11B;"
110
      ENTER Hp8720; Reply
120
      INPUT"CONNECT BROADBAND LOAD AT PORT 1", Dum$
130
      OUTPUT Hp8720; "CLASS11C; OPC?; STANA;"
140
      ENTER Hp8720; Reply
150
      INPUT"CONNECT OPEN AT PORT 2", Dum$
160
      OUTPUT Hp8720; "OPC?; CLASS22A;"
170
      ENTER Hp8720; Reply
180
      INPUT"CONNECT SHORT AT PORT 2", Dum$
190
      OUTPUT Hp8720; "OPC?; CLASS22B;"
200
      ENTER Hp8720; Reply
210
      INPUT"CONNECT BROADBAND LOAD AT PORT 2", Dum$
      OUTPUT Hp8720; "CLASS22C; OPC?; STANA;"
220
230
      ENTER Hp8720; Reply
240
      OUTPUT Hp8720; "REFD;"
250
      DISP "COMPUTING REFLECTION CALIBRATION COEFFICIENTS"
260
      OUTPUT Hp8720; "TRAN;"
270
      INPUT"CONNECT THRU [PORT1 TO PORT 2]", Dum$
280
      DISP "MEASURING FORWARD TRANSMISSION"
290
      OUTPUT Hp8720; "OPC?; FWDT; "
300
      ENTER Hp8720; Reply
310
      OUTPUT Hp8720;"OPC?;FWDM;"
320
      ENTER Hp8720; Reply
330
      DISP "MEASURING REVERSE TRANSMISSION"
      OUTPUT Hp8720; "OPC?; REVT; "
340
350
      ENTER Hp8720; Reply
360
      OUTPUT Hp8720; "OPC?; REVM;"
370
      ENTER Hp8720; Reply
```

```
380 OUTPUT Hp8720; "TRAD"
390 INPUT"ISOLATE TEST PORTS", Dum$
400 OUTPUT Hp8720; "ISOL;"
410 !OUTPUT Hp8720;"OMII;"
                                             !IF ISOLATION CAL NOT DESIRED
420 !GOTO 580
                                             !SKIP ISDLATION CAL SEQUENCE
430 DISP "MEASURING REVERSE ISOLATION"
440 OUTPUT Hp8720; "OPC?; REVI;"
450 ENTER Hp8720; Reply
460 DISP "MEASURING FORWARD ISOLATION"
470 OUTPUT Hp8720;"OPC?;FWDI;"
480 ENTER Hp8720; Reply
490 OUTPUT Hp8720; "ISOD;"
    DISP "COMPUTING CALIBRATION COEFFICIENTS"
510
520 OUTPUT Hp8720; "OPC?; SAV2;"
530 ENTER Hp8720; Reply
540 DISP "DONE"
550 OUTPUT Hp8720; "MENUON;"
560
     END
```

Figure 2-4. Sample Program: Full 2-port Measurement Calibration

Line 30	Begin by selecting the 3.5 mm cal kit and turning off the softkey menu.
Line 40	Open the calibration by calling for a full 2-port calibration type.
Line 50	Open the reflection calibration subsequence.
Line 60	Prompts for the OPEN connection and waits for an input to continue.
Line 70 and 80	Use operation complete for measurement of the S11A class.
Line 90	Prompts for the SHORT connection and waits for an input to continue.
Line 100 and 110	Use operation complete for measurement of the S11B class.
Line 120	Prompts for the BROADBAND LOAD connection and waits for an input to continue.
Line 130 and 140	Use operation complete for measurement of standard "A" in the S11C class.
Line 150 through 230	Measure port 2 reflection standards.
Line 240 and 250	Complete the reflection calibration subsequence.
Line 260 and 270	Open the transmission calibration subsequence.
Line 280 through 370	Measure the four transmission classes.
Line 380	Complete the transmission calibration subsequence.
Line 390 and 400	Open the isolation calibration subsequence.

Line 410 through 490 Measure the two isolation classes.

Line 510 through 550 Finish up by saving the error coefficient arrays and turning softkey menuing on.

Data Transfer from the Network Analyzer to a Computer

Trace information can be read out of the network analyzer in several ways. Data can be read off the trace selectively using the markers, or the entire trace can be read out.

Using Markers to Obtain Trace Data at Specific Points

If only specific information such as a single point off the trace or the result of a marker search is needed, the marker output command can be used to read the information.

Marker data is read out with the command OUTPMARK. This command causes the network analyzer to transmit three numbers: marker value 1, marker value 2, and marker stimulus value. Refer to Table 2-1 for all the different possibilities for values one and two.

```
10
20
      ! Using Markers to Obtain trace data at specific points
30
40
      Hp8720=716
50
      ABORT 7
60
      CLEAR Hp8720
70
80
      OUTPUT Hp8720; "PRES;"
90
      OUTPUT Hp8720; "CHAN1; S21; LOGM;"
100
      INPUT "Enter center frequency (Hz)",F_cent
110
      INPUT "Enter frequency span (Hz)",F_span
120
      OUTPUT Hp8720; "CENT "; F_cent
130
      OUTPUT Hp8720; "SPAN "; F_span
140
150
      OUTPUT Hp8720; "OPC;"
160
      OUTPUT Hp8720; "SING;"
170
      REPEAT
180
        OUTPUT Hp8720; "ESB?"
190
        ENTER Hp8720; Stat
200
      UNTIL BIT(Stat, 0)
210
      OUTPUT Hp8720; "AUTO; "
220
230
      OUTPUT Hp8720; "MARK1;"
240
      OUTPUT Hp8720; "SEAMIN;"
250
      OUTPUT Hp8720; "OUTPMARK;"
260
      ENTER Hp8720; Val1, Val2, Stim
270
      PRINT "Min val:", Val1; "dB"
280
      PRINT "Stimulus:", Stim; "Hz"
290
      END
```

Figure 2-5. Sample Program: Using Markers to Obtain Trace Data at Specific Points

Lines 150 through 200 Collects one sweep of data, and wait for completion. Line 220 Brings the trace data in view on the network analyzer's display.

Line 230 Activates marker 1.

Line 240 Search for the trace minimum.

Line 250 Outputs the marker values at that point.

Line 260 Reads marker value 1, marker value 2, and the stimulus value. In

log magnitude format, the marker value 2 is not significant, but is

included for contistency with all data transfers.

Table 2-1. Units as a Function of Display Format

Display Format	Marker Mode	OUTPMARK Marker Readout ¹ value 1, value 2	OUTPFORM value 1, value 2
LOG MAG		dB, ²	dB, ²
PHASE		degrees, ²	degrees, ²
DELAY		seconds,2	seconds, ²
SMITH	LIN MKR	lin mag, degrees	real, imag
CHART	LOG MKR Re/Im R + jX G + jB	dB, degrees real, imag real, imag ohms real, imag Siemens	real, imag real, imag real, imag real, imag
POLAR	LIN MKR LOG MKR Re/Im	lin mag, degrees dB, degrees real, imag	real, imag real, imag real, imag
LIN MAG		lin mag, ²	lin mag, ²
REAL		real, ²	real, ²
SWR		SWR, ²	SWR, ²

¹ The marker readout values are the marker values displayed in the upper right hand corner of the display. They also correspond to the value and aux value associated with the fixed marker.

² Value 2 not significant in this form, but is included in data transfers.

Trace Transfer

Getting trace data out of the network analyzer with a 200/300 series computer can be broken down into three steps:

- 1. Setting up the receive array.
- 2. Telling the network analyzer to transmit the data.
- 3. Accepting the transferred data.

Data inside the network analyzer is always stored in pairs, to accommodate real/imginary values, for each data point. Therefore, the receiving array has to be two elements wide, and as deep as the number of points. This memory space must be allocated in the computer (through a DIMension or ALLOCATE statement).

Data Format

The network analyzer can transmit data over HP-IB in five different formats. The type of format affects what kind of data array is declared (real or integer), since the format determines what type of data is transferred.

■ Form 1

Internal network analyzer format, 6 bytes per data point. The array is preceded by a four byte header. The first two bytes represent the string "#A", which is the standard block header. The second two bytes are an integer holding the number of bytes in the block to follow. This means that a 201 point transfer is 1210 bytes. Form 1 is intended for rapid data transfers to and from the computer, not for manipulation or subsequent processing by the computer.

■ Form 2

IEEE 32-bit floating point format, 8 bytes per data point. The array is preceded by a four byte header, The first two bytes represent the string "#A", which is the standard block header. The second two bytes are an integer holding the number of bytes in the block to follow. Each number consists of a sign bit, 8 bit signed exponent, and 23 bit mantissa. Two numbers make up a single data point. A 201 point transfer is 1612 bytes.

■ Form 3

IEEE 64-bit floating point format, 16 bytes per data point. The array is preceded by a four byte header, The first two hytes represent the string "#A", which is the standard block header. The second two bytes are an integer holding the number of bytes in the block to follow. Each number consists of a sign bit, 11 bit signed exponent, and 52 bit mantissa. Two numbers make up a single data point. A 201 point transfer is 2220 bytes.

■ Form 4

ASCII data transfer format. In this mode, each number is sent as a 24 character string, each character being a digit, sign, or decimal point. Since there are two numbers per point, a 201-point transfer is 9648 bytes.

Form 5

MS-DOS[®] personal computer format. This mode is a modification of IEEE 32-bit floating point format with the byte order reversed. The array is preceded by a four byte header. The first two bytes represent the string "#A", the standard block header. The second

two bytes are an integer holding the number of bytes in the block to follow, with the least significant byte preceding the most significant byte. Like Form 3, there are 8 bytes per data point, but the least significant byte precedes the more significant. Thus, in this format, an MS-DOS[®] PC can store data internally without reformatting it. A 201 point transfer is 1612 bytes.

Data Levels

Different levels of data can be read out of the network analyzer (Refer to Figure 1-3).

Raw data

The basic measurement data, which depends on the selection of the stimulus parameters, IF averaging, and IF bandwidth. If a full 2-port measurement calibration is ON, there are four raw arrays kept: one for each raw S-parameter. The data is read out with the commands OUTPRAW{1-4}. Otherwise, only raw array 1 is available, and it holds the current parameter. If a 2-port calibration is ON the four arrays correspond to S_{11} , S_{21} , S_{12} , and S_{22} respectively. This data is in real/imaginary pairs.

■ Error corrected data

This is the raw data with error correction applied. The array is for the currently measured parameter, and is in real/imaginary pairs. The error corrected data is read out with OUTPDATA. OUTPMEMO reads the trace memory if available, which is also error corrected. Neither raw nor error corrected data include the effects of post-processing functions, such as electrical delay offset or trace math.

■ Formatted data

This is the array of data being displayed. It includes the effects of all post-processing functions such as electrical delay, and the units of the array read out depends on the current display format. Refer to Table 2-1 for various units as a function of display format. The formatted data is read out with OUTPFORM.

Calibration coefficients

The results of a calibration are arrays of calibration coefficients (also called error coefficients) which are used in the error correction routines. Each array corresponds to a specific error term in the error model. The calibration coefficients are read out with OUTPCALC{01|12}.

Formatted data is generally the most useful, being the same information seen on the display. However, if the post-processing results are not necessary, error corrected data may be more desirable. Error corrected data also gives you the opportunity to load the data into the instrument and apply post-processing at a later time.

Data Transfer Using ASCII Transfer Format (Form 4)

When Form 4 is used, each number is sent as a 24 character string, each character being a digit, or decimal point. Since there are two numbers per point, a 201-point transfer in Form 4 takes 9648 bytes.

```
10
20
      ! Data Transfer using ASCII Transfer Format
30
      OPTION BASE 1
40
50
      Hp8720=716
60
      ABORT 7
70
      CLEAR Hp8720
80
      OUTPUT Hp8720; "PRES;"
90
      OUTPUT Hp8720; "CHAN1; S21; LOGM;"
100
110
      INPUT "Enter center frequency (Hz)",F_cent
120
      INPUT "Enter frequency span (Hz)", F_span
      OUTPUT Hp8720; "CENT "; F_cent
130
140
      OUTPUT Hp8720; "SPAN "; F_span
150
160
      OUTPUT Hp8720; "OPC?;"
170
      OUTPUT Hp8720; "SING;"
180
      ENTER Hp8720; Stat
190
200
      OUTPUT Hp8720; "POIN?;"
210
      ENTER Hp8720; Nump
220
      ALLOCATE Dat(Nump,2),Stim(Nump)
230
      OUTPUT Hp8720; "FORM4;"
240
250
      OUTPUT Hp8720; "OUTPFORM;"
260
      ENTER Hp8720;Dat(*)
270
280
     F_start=F_cent-F_span/2
290
     F_incre=F_span/(Nump-1)
300
310
     FOR I=1 TO Nump
320
       Stim(I)=F_start+F_incre*(I-1)
       PRINT Stim(I); "Hz", Dat(I,1); "dB"
330
340
      NEXT I
350
      DEALLOCATE Dat(*),Stim(*)
360
```

Figure 2-6. Sample Program: Data Transfer using ASCII Transfer Format (Form 4)

Line 40 Specifies the default lower bound of arrays to 1.

Lines 200 and 210 Finds out how many points to expect.

Line 220 Create arrays to hold the trace data and the stimulus data.

Line 230 Tells the network analyzer to use the ASCII transfer format.

Line 250 Requests the formatted trace data.

Line 260 Transfers the data from the network analyzer to the computer, and

puts it in the receiving array.

Calculates the stimulus value and prints the data. Also, it is possible Lines 310 through 340

to read the frequencies directly out of the network analyzer using the OUPTLIML command, which reports the limit test results by transmitting the stimulus point tested, a number indicating the limit test results, and then the upper and lower limits at the stimulus point. The number inidcating the limit results is a -1 for no test, 0 for fail and 1 for pass. If there are no upper or lower limits set, the

output for the limits is zeroes.

To try this, delete line 320 and edit lines 220, 280, 290, and 330 as

follows:

220 ALLOCATE Dat(Nump,2),Stim(Nump,4)

280 OUTPUT Hp8720; "OUTPLIML;" 290 ENTER Hp8720; Stim(*)

330 PRINT Stim(I,1); "Hz", Dat(I,1); "dB"

Line 350 Deallocates memory space.

Data Transfer using IEEE 64-bit Floating Point Format (Form 3)

Form 3 utilizes the IEEE 64-bit Floating Point Format for real numbers. The data transfer begins with a four byte header, the first two bytes correspond to the ASCII characters "#A" indicating a fixed length block transfer. The second two byte pair form an integer containing the number of bytes in the block to follow. Since Form 3 requires only 8 bytes for each number (compared to 24 bytes for ASCII Form 4), the data is transferred faster.

The transfer of data when using Form 3 is further enhanced by defining an I/O path with formatting OFF. Note the use of the ASSIGN statement below.

```
10
      ! Data Transfer using IEEE 64-bit Floating Point Format
20
30
      OPTION BASE 1
40
S0
      Hp8720=716
      ABORT 7
60
70
      CLEAR Hp8720
80
90
      OUTPUT Hp8720; "PRES;"
      OUTPUT Hp8720; "CHAN1; S21; LOGM;"
100
110
      INPUT "Enter center frequency (Hz)",F_cent
      INPUT "Enter frequency span (Hz)",F_span
120
      OUTPUT Hp8720; "CENT "; F_cent
130
      OUTPUT Hp8720; "SPAN "; F_span
140
1S0
      OUTPUT Hp8720; "OPC?;"
160
      OUTPUT Hp8720; "SING;"
170
180
      ENTER Hp8720; Stat
190
200
      OUTPUT Hp8720; "POIN?;"
210
      ENTER Hp8720; Nump
220
      ALLOCATE Dat(Nump,2),Stim(Nump)
230
      INTEGER Hdr, Lgth
      ASSIGN @Data TO Hp8720; FORMAT OFF
240
250
      OUTPUT Hp8720; "FORM3;"
260
270
      OUTPUT Hp8720; "OUTPFORM;"
      ENTER @Data; Hdr, Lgth, Dat(*)
280
290
300
      F_start=F_cent-F_span/2
      F_incre=F_span/(Nump-1)
310
320
330
      FOR I=1 TO Nump
        Stim(I)=F_start+F_incre*(I-1)
340
        PRINT Stim(I);"Hz",Dat(I,1);"dB"
350
      NEXT I
360
370
      DEALLOCATE Dat(*),Stim(*)
      ASSIGN @Data TO *
380
```

Figure 2-7. Sample Program: Data Transfer using IEEE 64-bit Floating Point Format (Form 3)

Sets up the I/O path; "FORMAT OFF" matches up the computer's real number format (IEEE 64-bit) to Form 3.
Tells network analyzer to output data using Form 3.
Enters the header, followed by the data.
Closes the I/O path.

Application Example

The following example is to measure the transmission parameter a bandpass filter and to get the typical parameters: -3 dB bandwidth, Center frequency, and Insertion loss.

```
10
20
      ! Bandpass Filter Test
30
40
      Hp8720=716
50
      ABORT 7
60
     CLEAR Hp8720
70
80
      OUTPUT Hp8720; "PRES;"
      OUTPUT Hp8720; "CHAN1; S21; LOGM;"
90
100
      INPUT "Enter center frequency (Hz)",F_cent
      INPUT "Enter frequency span (Hz)",F_span
110
120
      OUTPUT Hp8720; "CENT "; F_cent
130
      OUTPUT Hp8720; "SPAN "; F_span
140
150
      OUTPUT Hp8720; "HOLD;"
      OUTPUT Hp8720; "CALK35MM;"
160
      OUTPUT Hp8720; "CALIRESP;"
170
      INPUT "Connect THRU, then press [Return].", Dum$
180
190
      OUTPUT Hp8720;"OPC;"
200
      OUTPUT Hp8720; "STANC;"
210
      GOSUB Op_end
220
      OUTPUT Hp8720; "RESPDONE;"
      INPUT "Cal completed. Connect DUT, then press [Return].", Dum$
230
240
250
      OUTPUT Hp8720;"OPC;"
260
      OUTPUT Hp8720; "SING;"
270
      GOSUB Op_end
280
290
      OUTPUT Hp8720; "MARK1;"
300
      OUTPUT Hp8720; "SEAMAX;"
310
      OUTPUT Hp8720; "OUTPMARK;"
320
      ENTER Hp8720; Loss, Val2, Stim
330
340
      OUTPUT Hp8720; "DELR1;"
      OUTPUT Hp8720; "WIDV -3;"
350
      OUTPUT Hp8720; "WIDTON;"
360
370
      OUTPUT Hp8720; "OUTPMWID;"
380
      ENTER Hp8720; Bw, Cent, Q
390
      PRINT "-3 dB bandwidth:",Bw;"Hz"
400
410
      PRINT "Center frequency:", Cent; "Hz"
420
      PRINT "Insertion loss:",Loss;"dB"
430
      STOP
440
450 Op_end: !
```

```
460 REPEAT
470 OUTPUT Hp8720; "ESB?"
480 ENTER Hp8720; Stat
490 UNTIL BIT(Stat,0)
500 RETURN
510
     END
```

Figure 2-8. Sample Program: Application Example (Bandpass Filter Test)

Lines 80 through 130	Sets up measurement.
Lines 150 through 230	Does response calibration.
Lines 250 through 270	Takes one sweep of data.
Lines 290 through 320	Takes the insertion loss value using the marker search function.
Lines 340 through 380	Takes the -3 dB bandwidth value and the center frequency value using the bandwidth search function.

Advanced Programming Examples

Using List Frequency Mode

The list frequency mode lets you select the specific points or frequency spacing between points at which measurements are to be made. Sampling specific points reduces the measurement time since additional time is not spent measuring device characteristics at unnecessary frequencies.

This example shows how to create a list frequency table and transmit it to the network analyzer. The command sequence for entering a list frequency table imitates the key sequence followed when entering a table from the front panel: there is a command for every key press. Editing a segment is also the same as the key sequence, but the network analyzer automatically reorders each edited segment in order of increasing start frequency.

This example takes advantage of the computer's capabilities to simplify creating and editing the table. The table is entered and completely edited before being transmitted to the network analyzer. To simplify the programming task, options such as entering step size are not included.

A single segment of the list can be displayed and measured using the SSEGn command, where n=the segment number. The all segments command ASEG returns the network analyzer to the full frequency list.

```
10
20
      ! Using List Frequency Mode
30
40
      OPTION BASE 1
50
      Hp8720=716
60
      ABORT 7
70
      CLEAR Hp8720
80
90
      INPUT "Enter number of segments", Numb
100
      ALLOCATE Table(Numb,3)
110
120
      PRINTER IS 1
130
      OUTPUT 2; CHR$ (255) & "K";
140
      PRINT USING "10A,10A,10A,20A"; "Segment",
       "Start(Hz)", "Stop(Hz)", "Number of Points"
150
160
      FOR I=1 TO Numb
170
        GOSUB Loadpoin
180
      NEXT I
190
200
      LOOP
210
        INPUT "Do you want to edit? (Y/N)", An$
```

```
220
      EXIT IF An$="N" OR An$="n"
       INPUT "Enter segment number", I
230
240
        GOSUB Loadpoin
250
      END LOOP
260
      OUTPUT Hp8720;"PRES;"
270
280
       OUTPUT Hp8720; "CHAN1; S21; LOGM;"
290
300
      OUTPUT Hp8720; "EDITLIST;"
310
      OUTPUT Hp8720; "CLEL;"
320
      FOR I=1 TO Numb
330
        OUTPUT Hp8720; "SADD;"
340
        OUTPUT Hp8720; "STAR "; Table(I,1)
350
        OUTPUT Hp8720; "STOP "; Table(I,2)
360
        OUTPUT Hp8720; "POIN "; Table(I,3)
370
        OUTPUT Hp8720; "SDON;"
380
      NEXT I
390
      OUTPUT Hp8720; "EDITDONE;"
400
      OUTPUT Hp8720; "LISFREQ;"
420
430
      OUTPUT Hp8720; "OPC;"
440
      OUTPUT Hp8720; "SING;"
450
      REPEAT
460
        OUTPUT Hp8720; "ESB?"
470
       ENTER Hp8720; Stat
480
      UNTIL BIT(Stat,0)
490
      OUTPUT Hp8720; "AUTO;"
500
      STOP
510
520 Loadpoin:
530
      INPUT "Enter start frequency (Hz)",Table(I,1)
540
      INPUT "Enter stop frequency (Hz)",Table(I,2)
550
      INPUT "Enter number of points", Table(I,3)
560
     IF Table(I,3)=1 THEN Table(I,2)=Table(I,1)
570
      PRINT TABXY(0,I+1);I;TAB(10);Table(I,1);TAB(20);
      Table(I,2); TAB(35); Table(I,3)
580
     RETURN
590
     END
```

Figure 3-1. Sample Program: Using List Frequency Mode

Line 90 Finds out how many segments to expect.

Line 100 Creates a table to hold the segments. Keeps start frequency, stop

frequency, and number of points.

Lines 120 through 140 Clears the screen and print the table header.

Lines 160 through 180 Prompts for the start, stop, and number of points for each segment.

Lines 200 through 250 Edits the table until editing is no longer needed.

Line 300 Activates the frequency list edit mode, and opens the list frequency

table for editing.

Line 310 Deletes any existing segments.

Lines 320 through 380 Enters the segment values.

Line 390 Closes the table.

Line 400 Turns on list frequency mode.

Line 410 Displays the trace for only the listed frequency ranges.

Lines 520 through 580 Enters in a segment.

Lines 530 through 550 Enters the segment values.

Line 560 Makes the stop frequency equal to the start frequency to avoid

ambiguity, if only one point is in the segment.

Line 570 Prints the segment out.

Using Limit Lines to Perform Limit Testing

This example shows how to create a limit table and transmit it to the network analyzer. The command sequence for entering a limit table imitates the key sequence followed when entering a table from the front panel: there is a command for every key press. Editing a limit is also the same as the key sequence, but remember that the network analyzer automatically reorders the table in order of increasing start frequency.

This example takes advantage of the computer's capabilities to simplify creating and editing the table. The table is entered and completely edited before being transmitted to the network analyzer. To simplify the programming task, options such as entering offsets are not included.

```
10
20
      ! Setting up Limit Lines
30
40
      OPTION BASE 1
50
      Hp8720=716
60
      ABORT 7
70
      CLEAR Hp8720
08
90
      OUTPUT Hp8720; "PRES;"
100
      OUTPUT Hp8720; "CHAN1; S21; LOGM;"
110
      INPUT "Enter start frequency (Hz)",F_start
120
      INPUT "Enter stop frequency (Hz)",F_stop
130
      OUTPUT Hp8720; "STAR "; F_start
140
      OUTPUT Hp8720; "STOP "; F_stop
150
160
      INPUT "Enter number of limits", Numb
170
      ALLOCATE Table(Numb,3)
180
190
      PRINTER IS 1
200
      OUTPUT 2; CHR$ (255) & "K";
210
      PRINT USING "10A,15A,15A,15A"; "Segment",
       "Stimulus(Hz)", "Upper(dB)", "Lower(dB)"
220
230
      FOR I=1 TO Numb
240
        GOSUB Loadlimit
250
      NEXT I
260
270
      LOOP
280
        INPUT "Do you want to edit? (Y/N)", An$
      EXIT IF An$="N" OR An$="n"
290
300
        INPUT "Enter segment number", I
310
      GOSUB Loadlimit
      END LOOP
320
330
340
      OUTPUT Hp8720; "EDITLIML;"
350
      OUTPUT Hp8720; "CLEL;"
      FOR I=1 TO Numb
360
370
        OUTPUT Hp8720; "SADD;"
380
        OUTPUT Hp8720; "LIMS "; Table(I,1)
```

```
390
        OUTPUT Hp8720;"LIMU ";Table(I,2)
400
        OUTPUT Hp8720; "LIML "; Table(I,3)
410
        OUTPUT Hp8720; "SDON;"
420
      NEXT I
430
440
      OUTPUT Hp8720; "EDITDONE"
450
      OUTPUT Hp8720; "LIMILINEON"
      OUTPUT Hp8720; "LIMITESTON"
460
      DEALLOCATE Table(*)
470
480
      STOP
490
500 Loadlimit: !
     INPUT "Enter stimulus value (Hz)",Table(I,1)
510
520 INPUT "Enter upper limit value (dB)", Table(I,2)
530 INPUT "Enter lower limit value (dB)", Table(I,3)
540
     PRINT TABXY(0,I+1);I;TAB(11);Table(I,1);TAB(27);
      Table(I,2); TAB(42); Table(I,3)
550
     RETURN
560
     END
```

Figure 3-2. Sample Program: Setting up Limit Lines

Line 160	Finds out how many limits to expect.
Line 170	Creates a table to hold the limits. It will contain the stimulus value (frequency), the upper limit value, and the lower limit value.
Lines 190 through 210	Clears the screen and prints the table header.
Lines 230 through 250	Reads in each segment.
Lines 270 through 320	Edits the table until editing is no longer needed.
Line 340	Begins editing the limit line table.
Line 350	Deletes any existing limits.
Lines 360 through 420	Enters the segment values.
Line 440	Closes the table.
Line 450	Displays the limits.
Line 460	Activates the limit testing.
Lines 500 through 550	Enters a segment.

Storing and Recalling Instrument Status Coordinating disk storage

This example shows how to save and recall the instrument status in the disk installed in the built-in disk drive.

```
10
20
      ! Storing Instrument States
30
40 DIM Err$[50]
50 Hp8720=716
60 ABORT 7
70
    CLEAR Hp8720
80
90
      OUTPUT Hp8720; "PRES;"
      OUTPUT Hp8720; "CHAN1; S21; LOGM;"
110
      INPUT "Enter center frequency (Hz)",F_cent
      INPUT "Enter frequency span (Hz)",F_span
120
      OUTPUT Hp8720; "CENT "; F_cent
130
140
      OUTPUT Hp8720; "SPAN "; F_span
150
160
      INPUT "File name? (up to 8 char.)", Name$
      OUTPUT Hp8720; "USEPASC;"
170
180
      OUTPUT Hp8720; "TITF1"""; Name$; """; STOR1:"
      PASS CONTROL Hp8720
190
200
210
      STATUS 7,6; Stat
220
      IF NOT BIT(Stat,6) THEN GOTO 210
230
240
     INPUT "Save done. Press [Return] to recall.", Dum$
250
260
     OUTPUT Hp8720; "PRES;"
      OUTPUT Hp8720; "USEPASC;"
270
280
      OUTPUT Hp8720; "TITF1""; Name$; """; LOAD1; "
290
     PASS CONTROL Hp8720
300
     STATUS 7,6;Stat
310
     IF NOT BIT(Stat,6) THEN GOTO 300
320
330
     DISP "Done."
340
     END
```

Figure 3-3. Sample Program: Storing Instrument States

Line 160 Gets the name of the file to create.

Line 170 Enable the network analyzer to use the pass control capability.

Line 180 Saves the instrument states and the calibration coefficients with the

> file name. The file name must be preceded and followed by double quotation marks, and the only way to do that with an OUTPUT

statement is to use two sets of quotation marks: "".

Lines 190 The computer passes Active Controller to the network analyzer.

Lines 210 and 220 Wait for Active Controller status to return to the computer.

Line 260 through 310 Preset the network analyzer and recall the previously stored file.

Reading Calibration Data

This example demonstrates how to read measurement calibration data out of the network analyzer, and how to put it back into the network analyzer.

The data used to perform measurement error correction is stored inside the network analyzer in up to twelve calibration coefficient arrays. Each array is a specific error coefficient, and is stored and transmitted as an error corrected data array: each point is a real/imaginary pair, and the number of points in the array is the same as the number of points in the sweep. The four data formats also apply to the transfer of calibration coefficient arrays. HP-IB Programming Reference specifies where the calibration coefficients are stored for different calibration types.

The computer can read out the error coefficients using the OUTPCALC{01-12} commands. Each calibration type uses only as many arrays as needed, starting with array 1. Therefore, it is necessary to know the type of calibration about to be read out: attempting to read an array not being used in the current calibration causes the "REQUESTED DATA NOT CURRENTLY AVAILABLE" error message.

The computer can also input calibration coefficients to the network analyzer. To do this, declare the type of calibration data about to stored in the network analyzer just as if you were about to perform that calibration. Then, instead of calling up different classes, transfer the calibration coefficients using the INPUCALC{01-12} commands. When all the coefficients are in the network analyzer, activate the calibration by issuing the mnemonic SAVC, and have the network analyzer take a sweep.

This example reads the response calibration coefficients into a very large array, from which they can be examined, modified, stored, or put back into the network analyzer.

```
10
20
        Reading calibration data.
30
      ! It demonstrates how to read calibration data out
40
      ! of the network analyzer, and how to put it back in.
50
60
      ! The program will handle any type of calibration,
70
        and any number of points.
80
90
100
     Hp8720=716
     ABORT 7
110
120
      CLEAR Hp8720
130
     DATA "CALIRESP",1,"CALIRAI",2,"CALIS111",3
140
      DATA "CALIS221",3,"CALIFUL2",12,"CALITRL2",12
150
     DATA "NOOP",0
160
     INTEGER Hdr, Lgth, I, J
170
      ASSIGN @Data TO Hp8720; FORMAT OFF
180
190
     READ Calt$, Numb
200
     IF Numb=0 THEN GOTO 510
210
      OUTPUT Hp8720; Calt$;"?;"
220
     ENTER Hp8720; Active
230
      IF NOT Active THEN GOTO 190
```

```
240
250
      DISP Calt$, Numb
260
      OUTPUT Hp8720; "FORM3; POIN?; "
270
      ENTER Hp8720; Poin
280
      ALLOCATE Cal(1:Numb,1:Poin,1:2)
290
      FOR I=1 TO Numb
        OUTPUT Hp8720 USING "K,ZZ"; "OUTPCALC", I
300
        ENTER @Data; Hdr, Lgth
310
320
        FOR J=1 TO Poin
330
          ENTER @Data; Cal(I,J,1), Cal(I,J,2)
340
        NEXT J
350
      NEXT I
360
      !
370
      OUTPUT Hp8720; "CORROFF;"
380
390
      INPUT "Press [Return] to retransmit calibration data.", Dum$
400
      OUTPUT Hp8720; Calt$,";"
410
     FOR I=1 TO Numb
        DISP "TRANSMITTING ARRAY: ",I
420
430
        OUTPUT Hp8720 USING "K,ZZ"; "FORM3; INPUCALC", I
440
        OUTPUT @Data; Hdr, Lgth
450
        FOR J=1 TO Poin
460
          OUTPUT @Data; Cal(I,J,1), Cal(I,J,2)
470
        NEXT J
      NEXT I
480
490
      OUTPUT Hp8720; "SAVC;"
500
      OUTPUT Hp8720; "CONT;"
510
     DISP "DONE"
520
     END
```

Figure 3-4. Sample Program: Reading calibration data

Line 130 through 150	Set up the data base of possible calibrations, and the number of arrays associated with each calibration.
Line 190 through 230	Get a calibration type and the corresponding number of arrays for that calibration type. If correction was not one, exit the program. Query the network analyzer to determine if the calibration type is active; if not, loop back to read another type.
Line 250	Display the active calibration type and number of arrays.
Line 260 through 280	Establish Form 3 as the data transfer format; query the number of points. Allocate the required memory space based on the number of points.
Line 290 through 350	Request output of the appropriate calibration array; get the file header and calibration data for each array.
Line 400	Set up the calibration type for the arrays about to be loaded.

Line 410 through 480	Load each calibration array into the network analyzer.
Line 490	End of loading calibration array(s), save in internal network analyzer memory, and turn correction on.
Line 500	Set sweep to continuous to show that calibration arrays have been properly loaded.

Miscellaneous Programming Examples

Controlling Peripherals

The purpose of this section is to demonstrate how to coordinate printers or plotters with the network analyzer.

The network analyzer has three operating modes with respect to HP-IB, as set under the (LOCAL) menu: System controller, Talker/Listener, and Use Pass Control. The System Controller mode is used when no controller is present, and controls peripherals directly. The Talker/Listener mode is the most common most in which the computer controls the network analyzer. In the Use Pass Control mode, the network analyzer acts like a Talker/Listener, but additionally can take active control from the computer (System Controller) so that the network analyzer can directly control peripherals.

Note that the network analyzer assumes that the address of the computer is correctly stored in its HP-IB addresses menu under the ADDRESS: CONTROLLER entry. If this address is incorrect, control will not return to the computer.

This example shows control of a plotter with Talker/Listener mode.

```
10
20
         Operation using Talker/listener mode.
30
40
      Hp8720=716
      OUTPUT Hp8720; "OUTPPLOT; "
50
60
      SEND 7; UNL LISTEN 5 TALK 16 DATA
70
      DISP "PLOTTING"
80
      STATUS 7,7;Stat
      IF NOT BIT(Stat,11) THEN GOTO 80
90
100
      DISP "DONE"
110
      END
```

Figure 4-1. Sample Program: Using Talker/Listener Mode

Program explanation

Line 50 Command the network analyzer to plot.

Line 60

Use the HP Basic commands for HP-IB control to establish a data path from the network analyzer to the plotter. SEND 7 means that bus control commands will be sent from the Active Controller with select code 7. UNL forces all talker/listener instruments to "unlisten." LISTEN 5 commands the device at address 5 (the plotter) to now "listen" (wait for data). TALK 16 commands the network analyzer

to "talk" (send the data). DATA forces the HP-IB from "command" mode to "data" mode.

Line 70

Display that plotting is taking place, and provide momentary delay to prevent interrogation of status register 7.

Lines 80 through 90

Wait for the network analyzer to assert EOI, indicating end of transmission of data.

Using Pass Control Mode

This example shows control of a printer with Use Pass Control mode.

```
10
20
         Operation using pass control mode.
30
40
      Hp8720=716
      OUTPUT Hp8720; "CLES; ESE2; "
50
60
      OUTPUT Hp8720; "USEPASC; PRINALL;"
70
      Stat=SPOLL(Hp8720)
80
      IF NOT BIT(Stat,5) THEN GOTO 70
90
     PASS CONTROL Hp8720
    DISP "PRINTING"
100
110
     STATUS 7,6;Hpib
120
     IF NOT BIT(Hpib,6) THEN GOTO 110
130
     DISP "DONE"
140
     END
```

Figure 4-2. Sample Program: Using Pass Control Mode

Line 50	Clear the status reporting system. Enable the Request Active Control bit in the event status register.			
Line 60	Enable Use Pass Control. Request print.			
Lines 70 through 80	Wait until the network analyzer requests control.			
Line 90	Passes active control to the network analyzer.			
Line 110 through 120	Waits until the print is finished and the control is returned.			

Status and Error Reporting

The network analyzer has a status reporting mechanism that gives information about specific functions and events inside the network analyzer. The status byte is an 8-bit register with each bit summarizing the state of one aspect of the network analyzer. For example, the error queue summary bit will always be set if there are any errors in the queue. The value of the status byte can be read with the SPOLL statement. This command does not automatically put the network analyzer into the remote mode, thus giving the operator access to the network analyzer front panel functions. The status byte can also be read using the OUTPSTAT command, but the network analyzer will be put into remote mode. Reading the status byte does not affect its value.

The status byte also summarizes two event status registers that monitor specific conditions inside the network analyzer. The status byte also has a bit that is set when the network analyzer is issuing a service request over HP-IB, and a bit that is set when the network analyzer has data to send out over HP-IB. Refer to the HP-IB Programming Reference for a definition of the status registers.

The error queue holds up to 20 instrument errors and warnings in the order that they occurred. Each time the network analyzer detects an error condition and displays a warning message on the CRT, it also puts the error in the error queue. If there are any errors in the queue, bit 3 of the status byte will be set. The errors can be read from the queue with the OUTPERRO command, which causes the network analyzer to transmit the error number and the error message of the oldest error in the queue.

It is also possible to generate interrupts using the status reporting mechanism. The status byte bits can be enabled to generate a service request (SRQ) when set. The computer can in turn be set up to generate an interrupt on the SRQ.

To be able to generate an SRQ, a bit in the status byte has to be enabled using SRE n(Status Register Enable Mask). A one in a bit position enables that bit in the status byte. Therefore, SRE 8 enables an SRQ on bit 3, check error queue, since 8 equals 00001000 in binary representation. That means that whenever an error is put into the error queue and bit 3 gets set, and the SRQ line is asserted. The only way to clear the SRQ is to disable bit 3, re-enable bit 3, or read out all the errors from the queue.

A bit in the event status register can be enabled so that it is summarized by bit 5 of the status byte. If any bit is enabled in the event status register, bit 5 of the status byte will also be set. For example, ESE 66 (Event Status Enable Mask) enables bits 1 and 6 of the event status register, since 66 equals 01000010 in binary representation. Therefore, whenever active control is requested or a front panel key is pressed, bit 5 of the status byte will be set. Similarly, ESNB n enables bits in event status register B so that they will be summarized by bit 2 in the status byte.

To generate an SRQ from an event status register, enable the desired event status register bit. Then enable the status byte to generate an SRQ. For instance, *ESE 32 and *SRE 32 enable the syntax error bit, so that when the syntax error bit is set, the summary bit in the status byte will be set, and it enables an SRQ on bit 5 of the status byte.

```
10
20
      ! Generating Interrupts
30
40
      Hp8720=716
```

```
45
     DIM Err$[50]
50
60 OUTPUT Hp8720; "CLES;"
70
     OUTPUT Hp8720; "ESE 32;"
80
     OUTPUT Hp8720; "SRE 32;"
90
100
     ON INTR 7 GOSUB Err_report
110
     ENABLE INTR 7;2
120
130 LOOP
140 END LOOP
150 STOP
160
170 Err_report:!
180 Stat=SPOLL(Hp8720)
190 OUTPUT Hp8720; "ESR?"
200 ENTER Hp8720; Estat
210 PRINT "Syntax error detected."
220 !
230 OUTPUT Hp8720; "OUTPERRO;"
240 ENTER Hp8720; Err, Err$
250 PRINT Err, Err$
260 IF Erro THEN GOTO 230
270 ENABLE INTR 7
280 RETURN
290
    END
```

Figure 4-3. Sample Program: Generating Interrupts

Line 60	Clears the status reporting system.
Line 70	Enables bit 5 of the event status register.
Line 80	Enables bit 5 of the status byte so that an SRQ will generated on a syntax error.
Line 100	Tells the computer where to branch it gets the interrupt.
Line 110	Tells the computer to enable an interrupt from interface 7 (HP-IB) when value 2 (bit 1: SRQ bit) of the interrupt register is set. A branch to Err_report will disable the interrupt, so the return from Err_report re-enables it. Since there may be more than one instrument on the bus capable of generating an SRQ, it will be necessary to serial poll to determine that the network analyzer issued the SRQ. A branch to Err_report will disable the interrupt, so the return from Err_report re-enable it.
Line 130 and 140	Loop until interrupted.

Line 180 Clears the SRQ bit of the status byte. At the point, the variable

stat could have been checked to see if, in fact, the network analyzer

requested service.

Lines 190 and 200 Reads the register to clear the bit.

Lines 230 through 260 Instructs the network analyzer to output the error number and the

error message, and print them. The output will loop until no errors

(Err is 0).

Modifying Calibration Kit

The network analyzer has several calibration kit definitions built into the firmware. These can be called by using the CALKnnnn command. For example, the Type N 50 ohm kit (HP 85054D) can be selected using CALKN50.

For other calibration kits, and customizing the default kits, the following program shows how to perform the definition modification automatically.

```
10
      ! Creating an X band Calibration Kit Definition
20
      ! for the HP X11644A
30
     ASSIGN @Ana TO 716
90
    Minf=6.555E+9
100
                                               ! MIN. FREQUENCY
110
    Maxf=1.3111E+10
                                               ! MAX. FREQUENCY
    OUTPUT @Ana; "PRES; VELOFACTO.99968;"
120
130 OUTPUT @Ana; "SETZ1;";
                                               ! Set system imped to 1 ohm
140 ! Define standard #1
150 OUTPUT @Ana; "MODI1;";
                                               ! Modify cal kit #1 (8720)
    OUTPUT @Ana; "DEFS1;";
                                               ! Begin defining std # 1
160
170 OUTPUT @Ana;"STDTSHOR;";
                                               ! std #1 will be a short
    OUTPUT @Ana;"OFSDO;";
                                              ! offset delay = 0 ps
180
190 OUTPUT @Ana; "OFSLO; ";
                                               ! offset loss = 0
200 OUTPUT @Ana; "OFSZ1;";
                                               ! offset imped = 1 ohm
210 OUTPUT @Ana; "MINF", Minf; "HZ";
220 OUTPUT @Ana;"MAXF", Maxf;"HZ";
230 OUTPUT @Ana; "WAVE;";
                                               ! waveguide standard
240 OUTPUT @Ana; "STDD;";
                                              ! standard defined
250
     OUTPUT @Ana;"LABS""SHORT"";";
                                              ! label standard
260 ! Define standard #2
270
    OUTPUT @Ana; "DEFS2;";
                                               ! Begin defining std # 2
280 OUTPUT @Ana; "STDTSHOR; ";
                                              ! std #2 will be a short
    OUTPUT @Ana;"OFSD32.633PS;";
290
                                              ! offset delay
300 OUTPUT @Ana;"OFSLO;";
                                              ! offset loss = 0
310 OUTPUT @Ana;"OFSZ1;";
                                               ! offset imped = 1 ohm
320 OUTPUT @Ana; "MINF", Minf; "HZ";
330
    OUTPUT @Ana; "MAXF", Maxf; "HZ";
340
     OUTPUT @Ana; "WAVE;";
                                               ! waveguide standard
     OUTPUT @Ana; "STDD;";
350
                                               ! standard defined
     OUTPUT @Ana;"LABS""1/4 OFFSET"";";
360
                                               ! label standard
370
      ! Define standard #3
380
     OUTPUT @Ana; "DEFS3;";
                                               ! Begin defining std # 3
    OUTPUT @Ana; "STDTLOAD;";
390
                                               ! std #3 will be a load
400
     OUTPUT @Ana;"FIXE;"
                                               ! fixed load
410
     OUTPUT @Ana;"OFSDO;";
                                              ! offset delay = 0
420
     OUTPUT @Ana; "OFSLO;";
                                              ! offset loss = 0
     OUTPUT @Ana; "OFSZ1;";
430
                                               ! offset imped = 1 ohm
     OUTPUT @Ana; "MINF", Minf; "HZ";
440
450
      OUTPUT @Ana; "MAXF", Maxf; "HZ";
      OUTPUT @Ana; "WAVE;";
460
                                              ! waveguide standard
470
      OUTPUT @Ana; "STDD;";
                                               ! standard defined
```

```
480
      OUTPUT @Ana; "LABS""FIXED""; ";
                                              ! label standard
490
     ! Define standard #4
500
      OUTPUT @Ana; "DEFS4;";
                                              ! Begin defining std # 4
      OUTPUT @Ana; "STDTDELA;";
510
                                               ! std #4 will be a THRU
520
      OUTPUT @Ana;"OFSDO;";
                                              ! offset delay = 0
      OUTPUT @Ana;"OFSLO;";
530
                                              ! offset loss = 0
540
      OUTPUT @Ana; "OFSZ1;";
                                              ! offset imped = 1 ohm
      OUTPUT @Ana; "MINF", Minf; "HZ";
550
      OUTPUT @Ana; "MAXF", Maxf; "HZ";
560
570
      OUTPUT @Ana; "WAVE;";
                                               ! waveguide standard
580
      OUTPUT @Ana; "STDD;";
                                               ! standard defined
590
      OUTPUT @Ana; "LABS""THRU""; ";
                                               ! label standard
600
      ! Define standard #5
      OUTPUT @Ana; "DEFS5;";
610
                                              ! Begin defining std # 5
      OUTPUT @Ana;"STDTDELA;";
620
                                              ! std #5 will be a THRU
630
      OUTPUT @Ana;"OFSD32.633PS;";
                                              ! offset delay
640
      OUTPUT @Ana; "OFSLO;";
                                               ! offset loss = 0
      OUTPUT @Ana;"OFSZ1;";
650
                                               ! offset imped = 1 ohm
660
      OUTPUT @Ana; "MINF", Minf; "HZ";
670
      OUTPUT @Ana; "MAXF", Maxf; "HZ";
680
      OUTPUT @Ana; "WAVE;";
                                               ! waveguide standard
690
      OUTPUT @Ana; "STDD;";
                                               ! standard defined
      OUTPUT @Ana;"LABS""1/4 DELAY"";";
700
                                               ! label standard
710
      ! Specify the standards for a given class
      OUTPUT @Ana; "SPECRESP1,2,4;";
720
                                               ! response cal
730
      OUTPUT @Ana; "SPECRESI1,2,4;";
                                              ! response & isol
740
      OUTPUT @Ana; "SPECS11A1;";
                                              ! s11 class "A"
      OUTPUT @Ana; "SPECS11B2;";
750
                                              ! s11 class "B"
760
      OUTPUT @Ana; "SPECS11C3;";
                                              ! s11 class "C"
770
      OUTPUT @Ana; "SPECS22A1;";
                                              ! s22 class "A"
780
      OUTPUT @Ana; "SPECS22B2;";
                                             ! s22 class "B"
790
      OUTPUT @Ana; "SPECS22C3;";
                                              ! s22 class "C"
800
      OUTPUT @Ana; "SPECFWDT4;";
                                              ! forward trans.
810
      OUTPUT @Ana; "SPECFWDM4;";
                                              ! forward match
820
      OUTPUT @Ana; "SPECREVT4;";
                                              reverse trans.
      OUTPUT @Ana; "SPECREVM4;";
830
                                              ! reverse match
840
      OUTPUT @Ana; "CLAD;";
                                              ! class definitions done
850
      ! Label specific classes
      OUTPUT @Ana; "LABES11A""SHORT""; "; ! s11 class "A"
860
      OUTPUT @Ana;"LABES11B""1/4 SHORT"";";
870
                                              ! s11 class "B"
880
      OUTPUT @Ana; "LABES11C""FIXED LOAD""; "; ! s11 class "C"
890
      OUTPUT @Ana; "LABES22A" "SHORT""; ";
                                              ! s22 class "A"
      OUTPUT @Ana;"LABES22B""1/4 SHORT"";";
900
                                              ! s22 class "B"
910
      OUTPUT @Ana; "LABES22C" "FIXED LOAD""; "; ! s22 class "C"
      OUTPUT @Ana; "LABEFWDT""THRU""; ";
920
                                               ! fwd trans.
930
      OUTPUT @Ana; "LABEFWDM" "THRU""; ";
                                              fwd match
      OUTPUT @Ana; "LABEREVT" "THRU""; ";
940
                                               ! rev trans.
950
      OUTPUT @Ana; "LABEREVM" "THRU""; ";
                                              ! rev match
960
      ! Label kit
970
      OUTPUT @Ana;"LABK""WR90 A.O"";";
980
      ! Done with kit; save into nonvolatile mem
```

```
990 OUTPUT @Ana; "KITD; SAVEUSEK; CALKUSED;"

1000 ! Set up analyzer for waveguide freq range

1010 OUTPUT @Ana; "STAR8.2GHZ; STOP12.4GHZ;"

1011 OUTPUT @Ana; "TITF1" WR90A0"""

1012 OUTPUT @Ana; "WAVD", Minf; "HZ;"

1020 END
```

Figure 4-4. Sample Program: Creating a Waveguide Calibration Kit

Line 100	Set minimum frequency (waveguide cut-off frequency).
Line 110	Set the maximum frequency for rectangular waveguide TE10 mode.
Line 120	Preset the network analyzer and set velocity factor for dry air.
Line 130	Set system impedance so that measurements are normalized to 1 ohm.
Line 140 through 250	Define Standard #1 as a "short" with zero delay and label as "SHORT."
Line 260 through 360	Define Standard #2 as a "short" with 32.633 picosecond delay and label as "1/4 SHORT" (1/4 wavelength offset delay).
Line 360 through 480	Define Standard #3 as a "load" with zero delay and label as "FIXED."
Line 490 through 590	Define Standard #4 as a "delay/thru" with zero delay and label as "THRU."
Line 600 through 700	Define Standard #5 as a "delay/thru" with 32.633 picosecond delay and label as "1/4 DELAY" (1/4 wavelength offset delay).
Line 710 through 840	Specify the standard numbers to be measured under a specific class.
Line 850 through 950	Assign a label for a specific class.
Line 960 and 970	Label the cal kit definition.
Line 980 and 990	Save the cal kit definition into the USER KIT and select USER KIT.
Line 1000 and 1010	Set up the nominal frequency range for X band waveguide.
Line 1011	Title file position 1 with "WR90A0" so that a subsequent STORE TO DISK will use this file name.
Line 1012	Select waveguide delay and specify the waveguide cut-off frequency for the delay calculations.

Reading Binary Files

The network analyzer can store data files in ASCII or binary on a LIF formatted disk. The HP 9000 Series 200 or 300 computer can read a LIF formatted disk. The following program reads a network analyzer binary file into a data array.

```
10
20
      ! Reading Binary Files
30
40
      ABORT 7
      A$=""
50
60
      INPUT "File name? ",A$
70
      INPUT "Number of points? ",X
      ALLOCATE Dat(1:X,1:2)
80
      ASSIGN @Disk TO A$&":,700,0"; FORMAT OFF
90
100
     ENTER @Disk; Dat(*)
     PRINT Dat(*)
110
120
     END
```

Figure A-1. Sample Program: Reading Binary Files

```
Line 60 through 70
                        Input file name and number of points.
Line 80
                        Allocate a data array.
Line 90 through 100
                        Read file into data array.
Line 110
                        Display data array.
```